## VGP393 – Week 3

#### Agenda:

- Finding Concurrency
  - Program decompositions
  - Dependency analysis
  - Design evaluation
- Quiz #1
- Assignment #1 due
- Assignment #2 starts

Parallel programming is about finding and exploiting concurrency

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## **Problem Decompositions**

- Must decompose the problem into elements that can execute in parallel
- Decomposition occurs along two primary axes and one secondary axis
  - Task decomposition views the problem as a sequence of *tasks* that can be executed concurrently
  - Data decomposition views the data problem as separate chunks that can be evaluated concurrently
  - Data flow decomposition looks at how data flows through the program as the problem is solved

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# **Driving Forces**

Three forces drive all decompositions:

- Flexibility Is the design flexible enough to be adapted to changes in requirements?
  - Usually changes in problem size or changes in target system
- Efficiency Does the design scale to *at least* the number of processors in the target system?
  - Efficiency for one target system may come at the cost of flexibility to other systems
- Simplicity Can the program design be understood, debugged, and maintained?
  - Simplicity can come at a cost to efficiency

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## **Task Decomposition**

Look at the problem as a collection of tasks

- Look at the individual steps required to solve the problem
- Determine whether or not these steps are independent
- Find as many tasks as possible
  - Individual function calls
  - Iterations of a loop
  - Updates to portions of large data structures

## **Task Decomposition**

#### Evaluate the design...

- Flexibility Be flexible in the number of tasks
  - Parametrize the number and size of tasks at run-time
- Efficiency Two possibly opposing goals:
  - Tasks should be large enough to outweigh management overhead
  - Should be enough tasks to keep all PEs busy all the time
- Simplicity Tasks should be defined in such a way that debugging and maintenance are easy
  - Re-use code from sequential version of program

#### Works well if...

- Problem focuses on the manipulation of a large data structure
- The same or similar operations are performed on different parts of the structure in independent ways
- Focus on data structures that can be broken into chunks that can be operated on concurrently
  - Concurrency can be found in *array-based* computations by looking at updates to different segments of the array
    - Concurrent updates on *recursive data structures* can performed on different subtrees, etc.

#### Evaluate the design...

- Flexibility Be flexible in the size and number of data chunks
  - *Granularity knobs* are parameters in the program that, at runtime, control the size and number of data chunks
  - Granularity has a major impact on the overhead required to manage dependencies between the chunks
  - Dependencies should scale at a slower rate than effort required to compute each chunk

#### Evaluate the design...

- Efficiency An efficient design should evenly map work to UEs and not create too much additional management work
  - Size of data chunks must be large enough to dominate the amount of work required to manage the dependencies
  - Mapping chunks to UEs must also be considered. If the mapping is poor, some PEs will have much more work to do than others
  - Cache and memory access (NUMA) issues are important for data that must be shared

- Evaluate the design...
  - Simplicity Complex data mappings are difficult to debug
    - Abstract data types to control the mapping of global data to task-local data are useful



## **Data Flow Decomposition**

Look at how data flows from one task to another

- Hybrid of task decomposition and data decomposition
- Key feature is that one task cannot begin until it receives data from another task
  - Producer-consumer problems are the classic example
  - Understand the nature of the dependency between tasks
    - Seek to minimize the delay caused by the dependency

Parallel programming is about finding and exploiting concurrency



## **Dependency Analysis**

- Sometimes task decomposition generates sets of tasks that are entirely independent
  - These problems are often called *embarrassingly* parallel
- Dependencies are cases where the execution of one task affects the execution of another
  - Data-sharing dependencies can occur when tasks must share or exchange data during execution
  - Ordering constraints occur when tasks must execute in a certain order

## **Dependency Analysis**

Several common ordering constraints:

- Sequential (or data flow) dependency One task needs data generated by another task
- Parallel dependency A group of tasks *must* execute at the same time
- Independence Tasks are truly independent and can execute in any order



## **Group Tasks**

Grouping tasks simplifies dependency analysis

- Dependencies between groups can be resolved once per group instead of once per task in each group
- This principle guides the grouping...pick groupings that simplify the dependency analysis



# **Group Tasks**

Look at the original problem decomposition

- High-level operations or loops are central to most task decompositions
  - Tasks that correspond to high-level operations usually group together
  - Tasks within a high-level operation that share a constrain should remain as a separate group
- Merge groups that share a common constraint
  - Larger groups make scheduling and load balancing easier

## **Group Tasks**

Look at constraints between groups

- If groups have a clear ordering or a clear data flow, this is easy
- However, independent task groups may share constraints
  - It may be better to merge these groups



### Order Tasks

- How must task groups be ordered to satisfy all constraints?
- Create a partial ordering of tasks by identifying ordering constraints among groups
  - Ordering must be restrictive enough to satisfy all constraints
    - Design is not correct otherwise!
  - No more restrictive than necessary
    - Additional constraints limit flexibility in load balancing

### Order Tasks

For each group, identify data required before that group can execute

- To identify the ordering constraint, find the task / group that creates that data
- Determine if external services impose addition ordering constraints
  - Classic example is file I/O...different tasks may have to write data to a file in a particular order
- Also note when there is no constraint
  - Makes it more clear that potential interactions have
    been examined

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- Determine how and when data is shared among tasks
  - Data that is statically partitioned to particular tasks is task-local
  - Data that cannot be strictly associated with a particular task is shared
    - This is the source of most dependencies
  - Task may also need access to a *portion* of another task's data
    - Usually boundary data that neighbors that tasks local data

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- Impacts both correctness and efficiency of the program
  - Incorrect sharing can lead to some tasks getting incorrect data (reading before data is written)
  - Synchronization on global data can incur a lot of overhead
  - Excessive communication can also incur a lot of overhead
    - Condition variables, message queues, etc.

Identify data that is shared among tasks

- Look back at the original program decomposition for clues
- Classify each shared data
  - Read-only Data the is not modified does not need to be protected
  - Effectively-local Global data that is partitioned into per-UE subsets needs limited, if any, protection
  - Read/write Data that is both read and written arbitrarily needs the most synchronization

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Special cases of read / write data:

- Accumulate Partial results are accumulated together to form a final result
  - Typically each task has a copy of the data where it accumulates partial results
  - When all tasks are complete, each local copy is accumulated into the final result
- Multiple-read / single-write Data is read by multiple tasks, but only updated by one
  - All readers need the initial value
  - The writer can modify the data arbitrarilly

Two copies of the data are required (constant initial and modifyable)

Evaluate the design so far

- Decide whether or not to return to earlier steps or move on to the next step
- The earlier design flaws are caught, the easier they are to fix!



- Suitability for target platform
  - Does the design match the number of PEs available?
  - How is data shared among the PEs?
    - Different data partitionings fit SMP, NUMA, etc.
  - Are there sufficient UEs to mask I/O latency, etc?
  - Ratio of time spent doing useful work vs. overhead
    - Synchronization primitives (and available atomic operations) vary from platform to platform



#### Flexibility

- Flexible in the number of tasks generated?
- Is the definition of tasks independent of scheduling?
- Is the size of data chunks parameterizable?
- Does the algorithm handle boundary cases?



#### Efficiency

- Can the load be balanced amont PEs?
- Is overhead minimized?
  - Thread creation?
  - Synchronization?
  - Message passing?
  - etc.



#### Simplicity

Is the design as simple as possible without missing necessary components?



#### Other issues:

- How regular are tasks and their dependencies?
- Are interactions between tasks synchronous or asynchronous?
- Are tasks grouped in the best way?



#### References

# Much of this lecture comes from the following two sources:

Berna L. Massingill, Timothy G. Mattson, and Beverly A. Sanders; "Patterns for Finding Concurrency for Parallel Application Programs"; *Proceedings of the Seventh Pattern Languages of Programs Workshop* (*PLoP 2000*), 2000; http://jerry.cs.uiuc.edu/~plop/plop2k/proceedings/proceedings.html

Beverly Sanders, "A Pattern Language for Parallel Programming"; http://www.cise.ufl.edu/research/ParallelPatterns/sasplas.ppt

See also http://www.cise.ufl.edu/research/ParallelPatterns/

## Next week...

#### Algorithm structure

- Task Parallelism
- Divide and Conquer
- etc.
- Supporting Streutures
  - SPMD
  - Master / worker
  - Loop Parallelism
  - etc.

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